

## CYCLIC POLYGONS IN CLASSICAL GEOMETRY, II

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### Abstract

Formulas about the side lengths, diagonal lengths or radius of the circumcircle of a cyclic polygon, cyclic ideal polygon and cyclic hyperideal polygon in hyperbolic geometry can be unified.

**Key words:** cyclic polygon, ideal polygon, hyperideal polygon, hyperbolic geometry, diagonal, radius

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**1. Introduction.** In [1], the authors proved that a polynomial relation satisfied by the side lengths, diagonal lengths and circumradius of a Euclidean cyclic polygon is also satisfied by those of a hyperbolic or spherical cyclic polygon.

In this paper such a polynomial relation can be generalized to truncated ideal and truncated hyperideal polygons in hyperbolic geometry.

Suppose a hyperbolic polygon in the hyperbolic plane has vertices  $P_1, P_2, \dots, P_n$ . The distance between the vertices  $P_i$  and  $P_j$  is denoted by  $|P_i P_j|$  which is the length of either a side or a diagonal of the polygon.

If the points  $P_1, P_2, \dots, P_n$  are on a circle with finite radius, the polygon is a cyclic polygon.

Let  $H_1, H_2, \dots, H_n$  be  $n$  mutually disjoint horocycles in the hyperbolic plane. For each pair  $\{H_i, H_j\}$ , there is a unique geodesic segment perpendicular to both  $H_i$  and  $H_j$ , and the length of the segment realizes the distance between  $H_i$  and  $H_j$ . The distance between  $H_i$  and  $H_j$  is denoted by  $|H_i H_j|$ . In fact, if  $H_i$  and  $H_j$  are tangent to the ideal boundary of the hyperbolic plane at points  $Q_i$  and  $Q_j$ ,

the geodesic determined by  $Q_i$  and  $Q_j$  is perpendicular to both  $H_i$  and  $H_j$ . With these geodesic segments, the horocycles  $H_1, H_2, \dots, H_n$  determine a truncated ideal polygon.

If the horocycles  $H_1, H_2, \dots, H_n$  are tangent to a circle with finite radius, the truncated ideal polygon is a cyclic ideal polygon.

Let  $G_1, G_2, \dots, G_n$  be  $n$  mutually disjoint geodesics in the hyperbolic plane. For each pair  $\{G_i, G_j\}$ , there is a unique geodesic segment perpendicular to both  $G_i$  and  $G_j$ , and the length of the segment realizes the distance between  $G_i$  and  $G_j$ . The distance between  $G_i$  and  $G_j$  is denoted by  $|G_i G_j|$ . With these geodesic segments perpendicular to them, the geodesics  $G_1, G_2, \dots, G_n$  determine a truncated hyperideal polygon.

If the geodesics  $G_1, G_2, \dots, G_n$  are tangent to a circle with finite radius, the truncated hyperideal polygon is a cyclic hyperideal polygon.

**2. Triangle.** For a triangle in the hyperbolic plane, assume that it has the side lengths  $a, b, c$  and the radius of circumcircle  $r$ . Then

$$(1) \quad \frac{1}{4} \sinh^2 r = \frac{(\sinh \frac{a}{2} \sinh \frac{b}{2} \sinh \frac{c}{2})^2}{A_1(A_1 - 2 \sinh \frac{a}{2})(A_1 - 2 \sinh \frac{b}{2})(A_1 - 2 \sinh \frac{c}{2})},$$

where  $A_1 = \sinh \frac{a}{2} + \sinh \frac{b}{2} + \sinh \frac{c}{2}$ .

For three mutually disjoint horocycles tangent to a circle with finite radius  $r$  in the hyperbolic plane, assume the distances between the three pairs of horocycles are  $a, b, c$ . Then

$$(2) \quad \frac{1}{4} e^{2r} = \frac{e^{a+b+c}}{\left(e^{\frac{a}{2}} + e^{\frac{b}{2}} + e^{\frac{c}{2}}\right) \left(-e^{\frac{a}{2}} + e^{\frac{b}{2}} + e^{\frac{c}{2}}\right) \left(e^{\frac{a}{2}} - e^{\frac{b}{2}} + e^{\frac{c}{2}}\right) \left(e^{\frac{a}{2}} + e^{\frac{b}{2}} - e^{\frac{c}{2}}\right)}.$$

For three mutually disjoint geodesics tangent to a circle with finite radius  $r$  in the hyperbolic plane, assume the distances between the three pairs of geodesics are  $a, b, c$ . Then

$$(3) \quad \frac{1}{4} \cosh^2 r = \frac{(\cosh \frac{a}{2} \cosh \frac{b}{2} \cosh \frac{c}{2})^2}{A_{-1}(A_{-1} - 2 \cosh \frac{a}{2})(A_{-1} - 2 \cosh \frac{b}{2})(A_{-1} - 2 \cosh \frac{c}{2})},$$

where  $A_{-1} = \cosh \frac{a}{2} + \cosh \frac{b}{2} + \cosh \frac{c}{2}$ .

The three cases can be unified using the function introduced in [2]:

$$\tau_s(l) = \frac{1}{2}(e^l - se^{-l}) = \begin{cases} \sinh l & \text{for } s = 1, \\ \frac{1}{2}e^l & \text{for } s = 0, \\ \cosh l & \text{for } s = -1. \end{cases}$$

Equations (1), (2) and (3) are unified as, for  $s \in \{1, 0, -1\}$ ,

$$(4) \quad \frac{1}{4} \tau_s^2(r) = \frac{(\tau_s(\frac{a}{2})\tau_s(\frac{b}{2})\tau_s(\frac{c}{2}))^2}{A(A - 2\tau_s(\frac{a}{2}))(A - 2\tau_s(\frac{b}{2}))(A - 2\tau_s(\frac{c}{2}))},$$

where  $A = \tau_s(\frac{a}{2}) + \tau_s(\frac{b}{2}) + \tau_s(\frac{c}{2})$ .

In the following, we present a proof of equation (4). This proof serves as an example of the proof of the main result, Theorem 1.

**Proof of (4).** Let  $\alpha, \beta$  and  $\gamma$  be angles in  $(0, 2\pi)$  satisfying  $\alpha + \beta + \gamma = 2\pi$ . Then

$$\sin \frac{\gamma}{2} = \sin \left( \frac{\alpha}{2} + \frac{\beta}{2} \right) = \sin \frac{\alpha}{2} \cos \frac{\beta}{2} + \sin \frac{\beta}{2} \cos \frac{\alpha}{2}.$$

Therefore

$$\left( \sin \frac{\gamma}{2} - \sin \frac{\alpha}{2} \cos \frac{\beta}{2} \right)^2 = \sin^2 \frac{\beta}{2} \cos^2 \frac{\alpha}{2},$$

or

$$\sin^2 \frac{\gamma}{2} - 2 \sin \frac{\gamma}{2} \sin \frac{\alpha}{2} \cos \frac{\beta}{2} + \sin^2 \frac{\alpha}{2} \left( 1 - \sin^2 \frac{\beta}{2} \right) = \sin^2 \frac{\beta}{2} \left( 1 - \sin^2 \frac{\alpha}{2} \right)$$

which simplifies to

$$\sin^2 \frac{\gamma}{2} + \sin^2 \frac{\alpha}{2} - \sin^2 \frac{\beta}{2} = 2 \sin \frac{\gamma}{2} \sin \frac{\alpha}{2} \cos \frac{\beta}{2}.$$

Squaring both sides yields

$$\left( \sin^2 \frac{\gamma}{2} + \sin^2 \frac{\alpha}{2} - \sin^2 \frac{\beta}{2} \right)^2 = 4 \sin^2 \frac{\gamma}{2} \sin^2 \frac{\alpha}{2} \left( 1 - \sin^2 \frac{\beta}{2} \right)$$

which is equivalent to

$$(5) \quad 4 \left( \sin \frac{\alpha}{2} \sin \frac{\beta}{2} \sin \frac{\gamma}{2} \right)^2 = \left( \sin \frac{\alpha}{2} + \sin \frac{\beta}{2} + \sin \frac{\gamma}{2} \right) \left( -\sin \frac{\alpha}{2} + \sin \frac{\beta}{2} + \sin \frac{\gamma}{2} \right) \\ \times \left( \sin \frac{\alpha}{2} - \sin \frac{\beta}{2} + \sin \frac{\gamma}{2} \right) \left( \sin \frac{\alpha}{2} + \sin \frac{\beta}{2} - \sin \frac{\gamma}{2} \right).$$

Equation (4) will be derived from equation (5).

First, suppose  $P_1, P_2$  and  $P_3$  are vertices of a hyperbolic triangle with circumcentre  $O$  and circumradius  $r$ . Suppose the side lengths of the triangle are  $|P_1P_2| = a, |P_2P_3| = b$  and  $|P_3P_1| = c$ .

In the triangles  $\triangle OP_1P_2, \triangle OP_2P_3$  and  $\triangle OP_3P_1$ , by trigonometry

$$(6) \quad \sin \frac{\alpha}{2} = \frac{\sinh \frac{a}{2}}{\sinh r}, \quad \sin \frac{\beta}{2} = \frac{\sinh \frac{b}{2}}{\sinh r}, \quad \sin \frac{\gamma}{2} = \frac{\sinh \frac{c}{2}}{\sinh r}.$$

Second, let  $H_1, H_2$  and  $H_3$  be mutually disjoint horocycles tangent to a circle with centre  $O$  and radius  $r$ . Suppose  $|H_1H_2| = a, |H_2H_3| = b$  and  $|H_3H_1| = c$ . For each  $i = 1, 2, 3$ , let  $R_i$  denote the point of tangency between  $H_i$  and  $C$ . For

each  $i = 1, 2, 3$ , consider the generalized triangle of type  $(0, 0, 1)$  with sides  $OR_i$ ,  $OR_{i+1}$  and the common perpendicular to  $H_i$  and  $H_{i+1}$ , where  $H_4 = H_1$ . For more discussions of generalized triangles in hyperbolic plane, see [2].

In the three generalized triangles of type  $(0, 0, 1)$ , by trigonometry [2], we obtain

$$(7) \quad \sin \frac{\alpha}{2} = \frac{e^{\frac{a}{2}}}{e^r}, \quad \sin \frac{\beta}{2} = \frac{e^{\frac{b}{2}}}{e^r}, \quad \sin \frac{\gamma}{2} = \frac{e^{\frac{c}{2}}}{e^r}.$$

Third, let  $G_1$ ,  $G_2$  and  $G_3$  be mutually disjoint geodesics tangent to a circle with centre  $O$  and radius  $r$ . Suppose  $|G_1G_2| = a$ ,  $|G_2G_3| = b$  and  $|G_3G_1| = c$ . For each  $i = 1, 2, 3$ , let  $R_i$  denote the point of tangency between  $G_i$  and  $C$ . For each  $i = 1, 2, 3$ , consider the generalized triangle of type  $(-1, -1, 1)$  with sides  $OR_i$ ,  $OR_{i+1}$  and the common perpendicular to  $G_i$  and  $G_{i+1}$ , where  $G_4 = G_1$ .

In the three generalized triangles of type  $(-1, -1, 1)$ , by trigonometry [2], we obtain

$$(8) \quad \sin \frac{\alpha}{2} = \frac{\cosh \frac{a}{2}}{\cosh r}, \quad \sin \frac{\beta}{2} = \frac{\cosh \frac{b}{2}}{\cosh r}, \quad \sin \frac{\gamma}{2} = \frac{\cosh \frac{c}{2}}{\cosh r}.$$

The equations in (6), (7) and (8) can be unified as

$$(9) \quad \sin \frac{\alpha}{2} = \frac{\tau_s(\frac{a}{2})}{\tau_s(r)}, \quad \sin \frac{\beta}{2} = \frac{\tau_s(\frac{b}{2})}{\tau_s(r)}, \quad \sin \frac{\gamma}{2} = \frac{\tau_s(\frac{c}{2})}{\tau_s(r)}.$$

Substituting the expressions of  $\sin \frac{\alpha}{2}$ ,  $\sin \frac{\beta}{2}$  and  $\sin \frac{\gamma}{2}$  in equation (9) into equation (5), we get

$$4 \left( \tau_s\left(\frac{a}{2}\right) \tau_s\left(\frac{b}{2}\right) \tau_s\left(\frac{c}{2}\right) \right)^2 = \tau_s^2(r) \left( \tau_s\left(\frac{a}{2}\right) + \tau_s\left(\frac{b}{2}\right) + \tau_s\left(\frac{c}{2}\right) \right) \left( -\tau_s\left(\frac{a}{2}\right) + \tau_s\left(\frac{b}{2}\right) + \tau_s\left(\frac{c}{2}\right) \right) \\ \times \left( \tau_s\left(\frac{a}{2}\right) - \tau_s\left(\frac{b}{2}\right) + \tau_s\left(\frac{c}{2}\right) \right) \left( \tau_s\left(\frac{a}{2}\right) + \tau_s\left(\frac{b}{2}\right) - \tau_s\left(\frac{c}{2}\right) \right)$$

which is equivalent to equation (4). □

**3. Cyclic quadrilateral.** For a convex quadrilateral with vertices  $P_1$ ,  $P_2$ ,  $P_3$ ,  $P_4$  which lie on a circle with finite radius  $r$  in the hyperbolic plane, suppose the distance between the vertices are  $|P_1P_2| = a$ ,  $|P_2P_3| = b$ ,  $|P_3P_4| = c$ ,  $|P_4P_1| = d$ ,  $|P_1P_3| = e$ ,  $|P_2P_4| = f$ .

For four mutually disjoint horocycles  $H_1$ ,  $H_2$ ,  $H_3$ ,  $H_4$  which are tangent to a circle with finite radius  $r$  in the hyperbolic plane, suppose the distance between the vertices are  $|H_1H_2| = a$ ,  $|H_2H_3| = b$ ,  $|H_3H_4| = c$ ,  $|H_4H_1| = d$ ,  $|H_1H_3| = e$ ,  $|H_2H_4| = f$ .

For mutually disjoint geodesics  $G_1$ ,  $G_2$ ,  $G_3$ ,  $G_4$  which are tangent to a circle with finite radius  $r$  in the hyperbolic plane, suppose the distance between the vertices are  $|G_1G_2| = a$ ,  $|G_2G_3| = b$ ,  $|G_3G_4| = c$ ,  $|G_4G_1| = d$ ,  $|G_1G_3| = e$ ,  $|G_2G_4| = f$ .

In the three cases, the formulas representing diagonal lengths in terms of side lengths are

$$(10) \quad \tau_s^2\left(\frac{e}{2}\right) = \left(\tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{c}{2}\right) + \tau_s\left(\frac{b}{2}\right)\tau_s\left(\frac{d}{2}\right)\right) \frac{\tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{d}{2}\right) + \tau_s\left(\frac{b}{2}\right)\tau_s\left(\frac{c}{2}\right)}{\tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{b}{2}\right) + \tau_s\left(\frac{c}{2}\right)\tau_s\left(\frac{d}{2}\right)},$$

$$(11) \quad \tau_s^2\left(\frac{f}{2}\right) = \left(\tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{c}{2}\right) + \tau_s\left(\frac{b}{2}\right)\tau_s\left(\frac{d}{2}\right)\right) \frac{\tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{b}{2}\right) + \tau_s\left(\frac{c}{2}\right)\tau_s\left(\frac{d}{2}\right)}{\tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{d}{2}\right) + \tau_s\left(\frac{b}{2}\right)\tau_s\left(\frac{c}{2}\right)}.$$

The multiplication of the two equations implies Ptolemy's theorem

$$\tau_s\left(\frac{e}{2}\right)\tau_s\left(\frac{f}{2}\right) = \tau_s\left(\frac{a}{2}\right)\tau_s\left(\frac{c}{2}\right) + \tau_s\left(\frac{b}{2}\right)\tau_s\left(\frac{d}{2}\right).$$

When  $s = 0$ , it becomes

$$e^{\frac{1}{2}(e+f)} = e^{\frac{1}{2}(a+c)} + e^{\frac{1}{2}(b+d)}.$$

PENNER [3] proved that this formula holds for any decorated ideal quadrilateral and the distances  $a, b, c, d, e, f$  are allowed to be negative.

In fact, for example, if the horocycle  $H_1$  is shrunken away from the tangent circle by a distance  $x > 0$ , the distance  $|H_1H_2|$  becomes  $a+x$ , the distance  $|H_1H_3|$  becomes  $e+x$ , and the distance  $|H_4H_1|$  becomes  $d+x$ . Then Ptolemy's theorem still holds

$$e^{\frac{1}{2}(e+x+f)} = e^{\frac{1}{2}(a+x+c)} + e^{\frac{1}{2}(b+d+x)}.$$

For more discussion on this formula and its applications in theory of Teichmüller space and mathematical physics, see [4].

**Proof of (10), (11).** Let  $\alpha, \beta, \gamma$  and  $\delta$  be angles in  $(0, 2\pi)$  satisfying  $\alpha + \beta + \gamma + \delta = 2\pi$ .

We claim that

$$(12) \quad \sin^2 \frac{\alpha + \beta}{2} = \left(\sin \frac{\alpha}{2} \sin \frac{\gamma}{2} + \sin \frac{\beta}{2} \sin \frac{\delta}{2}\right) \frac{\sin \frac{\alpha}{2} \sin \frac{\delta}{2} + \sin \frac{\beta}{2} \sin \frac{\gamma}{2}}{\sin \frac{\alpha}{2} \sin \frac{\beta}{2} + \sin \frac{\gamma}{2} \sin \frac{\delta}{2}},$$

$$(13) \quad \sin^2 \frac{\alpha + \delta}{2} = \left(\sin \frac{\alpha}{2} \sin \frac{\gamma}{2} + \sin \frac{\beta}{2} \sin \frac{\delta}{2}\right) \frac{\sin \frac{\alpha}{2} \sin \frac{\beta}{2} + \sin \frac{\gamma}{2} \sin \frac{\delta}{2}}{\sin \frac{\alpha}{2} \sin \frac{\delta}{2} + \sin \frac{\beta}{2} \sin \frac{\gamma}{2}}.$$

To verify them, we start with

$$\cos \frac{\alpha + \beta}{2} + \cos \frac{\gamma + \delta}{2} = 0,$$

or

$$\left(\sin \frac{\alpha}{2} \sin \frac{\beta}{2} - \cos \frac{\alpha}{2} \cos \frac{\beta}{2}\right) + \left(\sin \frac{\gamma}{2} \sin \frac{\delta}{2} - \cos \frac{\gamma}{2} \cos \frac{\delta}{2}\right) = 0.$$

Multiplying  $2 \sin \frac{\alpha}{2} \sin \frac{\beta}{2} \sin \frac{\gamma}{2} \sin \frac{\delta}{2}$  on both sides of the above equation yields

$$\begin{aligned} & \left( 2 \sin^2 \frac{\alpha}{2} \sin^2 \frac{\beta}{2} - 2 \sin \frac{\alpha}{2} \sin \frac{\beta}{2} \cos \frac{\alpha}{2} \cos \frac{\beta}{2} \right) \sin \frac{\gamma}{2} \sin \frac{\delta}{2} \\ & \quad + \left( 2 \sin^2 \frac{\gamma}{2} \sin^2 \frac{\delta}{2} - 2 \sin \frac{\gamma}{2} \sin \frac{\delta}{2} \cos \frac{\gamma}{2} \cos \frac{\delta}{2} \right) \sin \frac{\alpha}{2} \sin \frac{\beta}{2} = 0, \end{aligned}$$

which is equivalent to

$$\begin{aligned} & \left( \sin^2 \frac{\alpha}{2} + \sin^2 \frac{\beta}{2} - \sin^2 \frac{\alpha + \beta}{2} \right) \sin \frac{\gamma}{2} \sin \frac{\delta}{2} \\ & \quad + \left( \sin^2 \frac{\gamma}{2} + \sin^2 \frac{\delta}{2} - \sin^2 \frac{\gamma + \delta}{2} \right) \sin \frac{\alpha}{2} \sin \frac{\beta}{2} = 0. \end{aligned}$$

Rearranging the terms yields

$$\begin{aligned} & \sin^2 \frac{\alpha + \beta}{2} \sin \frac{\gamma}{2} \sin \frac{\delta}{2} + \sin^2 \frac{\gamma + \delta}{2} \sin \frac{\alpha}{2} \sin \frac{\beta}{2} \\ & \quad = \left( \sin^2 \frac{\alpha}{2} + \sin^2 \frac{\beta}{2} \right) \sin \frac{\gamma}{2} \sin \frac{\delta}{2} + \left( \sin^2 \frac{\gamma}{2} + \sin^2 \frac{\delta}{2} \right) \sin \frac{\alpha}{2} \sin \frac{\beta}{2}. \end{aligned}$$

Using the fact  $\sin \frac{\alpha + \beta}{2} = \sin \frac{\gamma + \delta}{2}$  to the left-hand side and factorizing the right-hand side of the above equation, we have

$$\begin{aligned} & \sin^2 \frac{\alpha + \beta}{2} \left( \sin \frac{\alpha}{2} \sin \frac{\beta}{2} + \sin \frac{\gamma}{2} \sin \frac{\delta}{2} \right) \\ & \quad = \left( \sin \frac{\alpha}{2} \sin \frac{\gamma}{2} + \sin \frac{\beta}{2} \sin \frac{\delta}{2} \right) \left( \sin \frac{\alpha}{2} \sin \frac{\delta}{2} + \sin \frac{\beta}{2} \sin \frac{\gamma}{2} \right), \end{aligned}$$

which is equivalent to (12).

Equation (13) is derived by switching  $\beta$  and  $\delta$  in (12).

Using similar construction as in the case of triangles, for a cyclic quadrilateral, a cyclic truncated ideal quadrilateral or a cyclic truncated hyperideal quadrilateral with side lengths  $a, b, c, d$  and lengths of diagonals  $e, f$ , by trigonometry, we obtain

$$(14) \quad \begin{aligned} \sin \frac{\alpha}{2} &= \frac{\tau_s(\frac{a}{2})}{\tau_s(r)}, & \sin \frac{\beta}{2} &= \frac{\tau_s(\frac{b}{2})}{\tau_s(r)}, & \sin \frac{\gamma}{2} &= \frac{\tau_s(\frac{c}{2})}{\tau_s(r)}, & \sin \frac{\delta}{2} &= \frac{\tau_s(\frac{d}{2})}{\tau_s(r)}, \\ \sin \frac{\alpha + \beta}{2} &= \frac{\tau_s(\frac{e}{2})}{\tau_s(r)}, & \sin \frac{\alpha + \delta}{2} &= \frac{\tau_s(\frac{f}{2})}{\tau_s(r)}, \end{aligned}$$

where the angles  $\alpha, \beta, \gamma, \delta$  have vertex  $O$ , the centre of the circumcircle, and are opposite to the sides of lengths  $a, b, c, d$ , respectively.

Then equations (10) and (11) are obtained by substituting (14) into equations (12) and (13).  $\square$

**4. Cyclic polygons.** Recall that, in [1],  $\mathcal{H}_n$  is defined as the set of polynomials  $h$  of  $\frac{n(n-1)}{2} + 1$  variables<sup>1</sup> such that

$$h\left(\sinh \frac{|P_i P_j|}{2}, \frac{1}{2} \sinh r\right) = 0$$

for any  $n$  points  $P_1, P_2, \dots, P_n$  on a circle of radius  $r$  in the hyperbolic plane.

Now we define  $\mathcal{H}_n^1$  to be the set of polynomials  $f$  of  $\frac{n(n-1)}{2} + 1$  variables such that

$$f\left(\sinh \frac{|P_i P_j|}{2}, \sinh r\right) = 0$$

for any  $n$  points  $P_1, P_2, \dots, P_n$  on a circle of radius  $r$  in the hyperbolic plane.

There exists a bijection between  $\mathcal{H}_n$  and  $\mathcal{H}_n^1$ . A polynomial  $h(y_{12}, y_{13}, \dots, y_{n-1,n}, z)$  belongs to  $\mathcal{H}_n$  if and only if the polynomial

$$f(y_{12}, y_{13}, \dots, y_{n-1,n}, z) = h\left(y_{12}, y_{13}, \dots, y_{n-1,n}, \frac{1}{2}z\right)$$

belongs to  $\mathcal{H}_n^1$ .

As an analogue,  $\mathcal{H}_n^0$  is defined as the set of polynomials  $f$  of  $\frac{n(n-1)}{2} + 1$  variables such that

$$f\left(\frac{1}{2}e^{\frac{|H_i H_j|}{2}}, \frac{1}{2}e^r\right) = 0$$

for any  $n$  mutually disjoint horocycles  $H_1, H_2, \dots, H_n$  tangent to a circle of radius  $r$  in the hyperbolic plane.

And  $\mathcal{H}_n^{-1}$  is defined as the set of polynomials  $f$  of  $\frac{n(n-1)}{2} + 1$  variables such that

$$f\left(\cosh \frac{|G_i G_j|}{2}, \cosh r\right) = 0$$

for any  $n$  mutually disjoint geodesics  $G_1, G_2, \dots, G_n$  tangent to a circle of radius  $r$  in the hyperbolic plane.

**Theorem 1.**  $\mathcal{H}_n^1 = \mathcal{H}_n^0 = \mathcal{H}_n^{-1}$ .

In fact, a polynomial in the set  $\mathcal{H}_n^1 = \mathcal{H}_n^0 = \mathcal{H}_n^{-1}$  can be expressed uniformly as

$$f\left(\tau_s\left(\frac{l_{ij}}{2}\right), \tau_s(r)\right) = 0,$$

where  $l_{ij}$  is the distance between two points, two disjoint horocycles or two disjoint geodesics.

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<sup>1</sup>The error in [1] regarding the use of “ $\frac{n(n+1)}{2}$  variables” is corrected here.

**5. Homogeneity.** To prove Theorem 1, we need the following lemma.

**Lemma 2.** *If  $f \in \mathcal{H}_n^1 \cup \mathcal{H}_n^0 \cup \mathcal{H}_n^{-1}$ , then  $f$  is homogeneous.*

**Proof.** It is proved in [1] that any  $f \in \mathcal{H}_n$  is homogeneous. The bijection between  $\mathcal{H}_n$  and  $\mathcal{H}_n^1$  implies that any  $f \in \mathcal{H}_n^1$  is also homogeneous.

Assume  $f \in \mathcal{H}_n^0$ . Then

$$f\left(\frac{1}{2}e^{\frac{|H_i H_j|}{2}}, \frac{1}{2}e^r\right) = 0$$

for  $n$  mutually disjoint horocycles  $H_1, H_2, \dots, H_n$  tangent to a circle  $C$  of radius  $r$  in the hyperbolic plane. Let  $C'$  be the circle with the same centre of circle  $C$  and radius  $r + x$  with  $x > 0$ . Let  $H'_i$  be the horocycle which is tangent to the ideal boundary of the Poincaré disk at the same point as  $H_i$  and is tangent to the circle  $C'$ . Then  $|H'_i H'_j| = |H_i H_j| + 2x$ . So the relation is also satisfied for the horocycles  $H'_i$ 's and the circle  $C'$ :

$$f\left(\frac{1}{2}e^{\frac{|H_i H_j| + 2x}{2}}, \frac{1}{2}e^{r+x}\right) = 0.$$

Therefore  $f$  is homogeneous since the above equation holds for any  $x > 0$ .

Assume  $f \in \mathcal{H}_n^{-1}$ . Then

$$f\left(\cosh \frac{|G_i G_j|}{2}, \cosh r\right) = 0$$

for  $n$  mutually disjoint geodesics  $G_1, G_2, \dots, G_n$ , each of which is tangent to a circle  $C$  with centre  $O$  and radius  $r$  in the hyperbolic plane. Suppose  $O$  is the origin. Let  $R_i$  denote the point of tangency between  $G_i$  and  $C$ , for each  $i = 1, 2, \dots, n$ .

A hyperbolic geodesic  $G_i$  is a portion of a Euclidean circle with centre  $O_i$  and perpendicular to the ideal boundary of the Poincaré disk. Let  $l$  be a straight line passing through  $O$  and  $O_i$ . Then  $l$  is perpendicular to  $G_i$  and passes through the point  $R_i$ .

Consider the generalized triangle of type  $(-1, -1, 1)$  with sides  $OR_i, OR_j$  and the common perpendicular to  $G_i$  and  $G_j$ . It has side lengths  $r, r$  and  $|G_i G_j|$ . Half of this triangle forms a right triangle, to which we apply the sine law for a generalized hyperbolic triangle [2], yielding

$$\frac{\sin \frac{\angle R_i O R_j}{2}}{\cosh \frac{|G_i G_j|}{2}} = \frac{\sin \frac{\pi}{2}}{\cosh r}.$$

Let  $C'$  be the circle with centre  $O$  and radius  $r + x$  with  $x > 0$ . For each  $i$ , let  $G'_i$  be the hyperbolic geodesic tangent to the circle  $C'$ , and be a portion of Euclidean circle with centre  $O'_i \in l$  and perpendicular to the ideal boundary of



the Poincaré disk. Let  $R'_i$  denote the point of tangency between  $G'_i$  and  $C$ . Then  $l$  is perpendicular to  $G'_i$  and passes through the point  $R'_i$ .

In fact,  $G_i$  and  $G'_i$  determine a hyperbolic pencil of geodesics perpendicular to  $l$ . For more discussion on hyperbolic pencils, see [5, p. 72] and [6, p. 168].

Similarly, by the sine law for a generalized hyperbolic triangle, we have

$$\frac{\sin \frac{\angle R'_i O R'_j}{2}}{\cosh \frac{|G'_i G'_j|}{2}} = \frac{\sin \frac{\pi}{2}}{\cosh(r+x)}.$$

Since  $\angle R'_i O R'_j = \angle R_i O R_j$ , we have

$$\cosh \frac{|G_i G_j|}{2} \frac{\cosh(r+x)}{\cosh r} = \cosh \frac{|G'_i G'_j|}{2}.$$

Since the relation holds also for the geodesics  $G'_i$ 's and circle  $C'$ :

$$f \left( \cosh \frac{|G'_i G'_j|}{2}, \cosh(r+x) \right) = 0.$$

Then

$$0 = f \left( \cosh \frac{|G_i G_j|}{2} \frac{\cosh(r+x)}{\cosh r}, \cosh(r+x) \right) = f \left( y \cosh \frac{|G_i G_j|}{2}, y \cosh r \right)$$

for an arbitrary  $y = \frac{\cosh(r+x)}{\cosh r}$ . Therefore  $f$  is homogeneous.  $\square$

**6. Relations of angles.** Let  $O$  be a point in the hyperbolic plane, and let  $l_1, \dots, l_n$  be a family of geodesic rays emanating from  $O$ , with each ray  $l_{i+1}$  obtained from  $l_i$  by a counterclockwise rotation, for  $i = 1, \dots, n$ , and  $l_{n+1} = l_1$ . Let  $\theta_{ij} \in (0, 2\pi)$  denote the angle between  $l_i$  and  $l_j$ . The ambiguity between  $\theta_{ij}$  and  $2\pi - \theta_{ij}$  is irrelevant, as only  $\sin \frac{\theta_{ij}}{2}$  will be used.

Let  $\mathcal{A}_n$  be the set of all polynomials  $g$  in the  $\frac{n(n-1)}{2}$  variables  $x_{ij}$ , where  $1 \leq i < j \leq n$ , such that  $g \left( \sin \frac{\theta_{12}}{2}, \sin \frac{\theta_{13}}{2}, \dots, \sin \frac{\theta_{n-1,n}}{2} \right) = 0$ .

For a polynomial  $g(x_{12}, x_{13}, \dots, x_{n-1,n}) \in \mathcal{A}_n$  of degree  $m$ , the homogenization of  $g$  produces a homogeneous polynomial  $g^*$ , defined by the relation

$$g^*(y_{12}, y_{13}, \dots, y_{n-1,n}, z) = z^m g \left( \frac{y_{12}}{z}, \frac{y_{13}}{z}, \dots, \frac{y_{n-1,n}}{z} \right).$$

To prove Theorem 1, we will show that each of  $\mathcal{H}_n^1$ ,  $\mathcal{H}_n^0$  and  $\mathcal{H}_n^{-1}$  equals  $\mathcal{A}_n^* = \{g^* : g \in \mathcal{A}_n\}$ .

**Proof of Theorem 1.** First, let  $P_1, \dots, P_n$  be  $n$ -points in a circle with centre  $O$  and radius  $r$  in the hyperbolic plane. Let  $l_i$  be the geodesic ray from  $O$  to  $P_i$ .

In the triangle  $\triangle OP_iP_j$ , by trigonometry, we have

$$\frac{\sin \frac{\theta_{ij}}{2}}{\sinh \frac{|P_iP_j|}{2}} = \frac{\sin \frac{\pi}{2}}{\sinh r}$$

then

$$\sin \frac{\theta_{ij}}{2} = \frac{\sinh \frac{|P_iP_j|}{2}}{\sinh r}.$$

Second, let  $H_1, \dots, H_n$  be  $n$  mutually disjoint horocycles tangent to a circle with centre  $O$  and radius  $r$  in the hyperbolic plane. Let  $l_i$  be the geodesic ray from  $O$  to the tangent point in  $H_i$ .

For each  $i$ , let  $R_i$  denote the point of tangency between  $H_i$  and the circle. In the generalized triangle of type  $(0, 0, 1)$  with sides  $OR_i, OR_j$  and the common perpendicular to  $H_i$  and  $H_j$ , by trigonometry [2], we have

$$\sin \frac{\theta_{ij}}{2} = \frac{\frac{1}{2}e^{\frac{|H_iH_j|}{2}}}{\frac{1}{2}e^r}.$$

Third, let  $G_1, \dots, G_n$  be  $n$  mutually disjoint geodesics tangent to a circle with centre  $O$  and radius  $r$  in the hyperbolic plane. Let  $l_i$  be the geodesic ray from  $O$  to the tangent point in  $G_i$ .

For each  $i$ , let  $R_i$  denote the point of tangency between  $G_i$  and the circle. In the generalized triangle of type  $(-1, -1, 1)$  with sides  $OR_i, OR_j$  and the common perpendicular to  $G_i$  and  $G_j$ , by trigonometry [2], we have

$$\sin \frac{\theta_{ij}}{2} = \frac{\cosh \frac{|G_iG_j|}{2}}{\cosh r}.$$

The three cases can be unified as

$$\sin \frac{\theta_{ij}}{2} = \frac{\tau_s \left( \frac{l_{ij}}{2} \right)}{\tau_s(r)},$$

where  $l_{ij}$  is the distance between two points, two disjoint horocycles or two disjoint geodesics.

If a polynomial  $g$  in  $\frac{n(n-1)}{2}$  variables belongs to  $\mathcal{A}_n$ , then

$$g \left( \sin \frac{\theta_{12}}{2}, \sin \frac{\theta_{13}}{2}, \dots, \sin \frac{\theta_{n-1,n}}{2} \right) = 0,$$

which implies

$$g \left( \frac{\tau_s \left( \frac{l_{12}}{2} \right)}{\tau_s(r)}, \frac{\tau_s \left( \frac{l_{13}}{2} \right)}{\tau_s(r)}, \dots, \frac{\tau_s \left( \frac{l_{n-1,n}}{2} \right)}{\tau_s(r)} \right) = 0.$$

Let  $m$  be the degree of  $g$ , multiplying  $\tau_s^m(r)$  on both sides of the above equation which yields

$$g^* \left( \tau_s \left( \frac{l_{12}}{2} \right), \tau_s \left( \frac{l_{13}}{2} \right), \dots, \tau_s \left( \frac{l_{n-1,n}}{2} \right), \tau_s(r) \right) = 0.$$

This establishes that  $g^* \in \mathcal{H}_n^s$  for  $s \in \{1, 0, -1\}$ .

On the other hand, if a polynomial  $f$  in  $\frac{n(n-1)}{2} + 1$  variables belongs to  $\mathcal{H}_n^s$  for  $s \in \{1, 0, -1\}$ , then

$$f \left( \tau_s \left( \frac{l_{12}}{2} \right), \tau_s \left( \frac{l_{13}}{2} \right), \dots, \tau_s \left( \frac{l_{n-1,n}}{2} \right), \tau_s(r) \right) = 0.$$

Since  $f$  is homogeneous, we have

$$f \left( \frac{\tau_s \left( \frac{l_{12}}{2} \right)}{\tau_s(r)}, \frac{\tau_s \left( \frac{l_{13}}{2} \right)}{\tau_s(r)}, \dots, \frac{\tau_s \left( \frac{l_{n-1,n}}{2} \right)}{\tau_s(r)}, 1 \right) = 0.$$

It becomes

$$f \left( \sin \frac{\theta_{12}}{2}, \sin \frac{\theta_{13}}{2}, \dots, \sin \frac{\theta_{n-1,n}}{2}, 1 \right) = 0.$$

Rewrite  $g(x_{12}, x_{13}, \dots, x_{n-1,n}) = f(x_{12}, x_{13}, \dots, x_{n-1,n}, 1)$ . Then  $g$  is a polynomial in  $\mathcal{A}_n$  and  $f = g^*$ .  $\square$

**Remark.** This proof also works for Euclidean and spherical geometry. So there is a one-to-one correspondence between  $\mathcal{E}_n$  (or  $\mathcal{S}_n$ ) and  $\mathcal{A}_n^*$ . This provides another proof of Theorem 1 in [1].

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